

**CHCNAV**

# CGI-230

**HIGH-PRECISION COMBINED  
INERTIAL GUIDANCE SYSTEM**



**NAVIGATION &  
INFRASTRUCTURE**





## HIGH-PRECISION COMBINED INERTIAL GUIDANCE SYSTEM

CGI-230 is a new generation of automotive-grade high-precision tight combination inertial guidance system launched by CHCNAV. Based on the full-system full-frequency point GNSS module and 6-axis tactical IMU, the product adopts CHCNAV's new generation of closely coupled algorithm engine, and through the fusion and solution of GNSS, INS, DR information, it can still provide continuous and high-precision navigation information such as position, speed and attitude in urban canyons, urban overpass, tree-shade, high-speed, park and other satellite signal occlusion or multipath scenarios, which has a higher fixed rate and robustness than the loosely coupled algorithm.

The product supports serial port, 100Base-T1 automotive Ethernet, CANFD and other communication methods; based on Autosar software architecture development, it supports fault messages, UDS diagnosis, gPTP/CanTsyn, PPS time synchronization scheme, and supports general vehicle, low-speed carrier and other modes.

Provide stable and reliable high-precision PVAT solutions for logistics and distribution, park cleaning, low-speed robots, RoboTaxi, trunk line logistics, intelligent agricultural machinery and other industries.

## AREAS OF APPLICATION



Park Logistics



Agricultural farmland



Autonomous Vehicle Driving



Dry logistics

## SPECIFICATIONS

GNSS Performance Indicators									
Signal tracking	BDS: B1/B2/B3 GPS: L1/L2/L5 GLONASS: L1/L2 Galileo: E1/E5a/E5b QZSS: L1/L2/L5								
Positioning accuracy (RMS)	Single: L1/L2: 1.2 m DGPS: 0.4 m RTK: 1 cm+1 ppm (Horizontal), 2 cm+1 ppm (Altitude)								
Heading accuracy (RMS)	0.1°/2 m baseline								
RTK solution frequency	20 Hz (max) <sup>[1]</sup>								
Speed accuracy (RMS)	0.03 m/s								
PPS time synchronization accuracy (RMS)	20 ns								
Cold start time (RMS)	≤35 s								
IMU Performance Specifications									
IMU type	MEMS								
Gyro output operating range	±300 °/s								
Gyro bias instability (Allan 1σ)	1.8 °/h								
Accelerometer output operating range (Allan 1σ)	±6 g								
IMU Performance Specifications									
Accelerometer bias instability (Allan 1σ) ≤15 ug									
Accelerometer angular random walk (Allan 1σ) 0.035 m/s/√hr									
Fusion output frequency 100 Hz									
Communication Interface									
External interface Primary connector: 1×power, 3×RS232,1×PPS,2×CANFD, 1×100Base-T1,2×Antenna RF interface									
Environmental									
Operating temperature -40°C ~ +75°C									
Storage temperature -40°C ~ +85°C									
Humidity 95% non-condensing									
Protection class IP52									
Physical Dimensions and Electrical Characteristics									
Power input 9~32 V DC (Standard Adaptation 12 V DC)									
Power consumption <4 W (typical)									
Physical dimensions 154×105×35 mm									
Weight <400 g (without antenna and cable)									
Performance during GNSS outages RMS <sup>[2]</sup>									
GNSS outage duration		Positioning mode		Location accuracy (m)		Velocity accuracy (m/s)		Attitude accuracy (°)	
				Horizontal	Vertical	Horizontal	Vertical	Heading	Attitude
0s		RTK		0.02	0.03	0.02	0.01	0.08	0.08
10s		RTK		0.2	0.1	0.05	0.02	0.12	0.09

Note 1: 20Hz RTK data output, need to use GNSS special RS232\_B port.

Note 2: The GNSS interruption and loss of lock test is conducted based on typical urban tunnel test scenarios for passenger vehicles and is for reference only. The test results may vary depending on the type of carrier, carrier speed, and application environment. Please refer to the actual test scenarios for accurate results. The parameter values listed in this document are either theoretical values or values measured by CHCNAV personnel under specific controlled test conditions. Due to individual product differences, firmware versions, and usage conditions, the actual values during usage may vary. Please refer to the actual usage conditions. To provide the most accurate product information and parameter values, CHCNAV may make real-time adjustments and corrections to the text, parameter values, and other content in this document to match the actual product performance, specifications, and other information. Due to real-time changes in product batches and production supply factors, we may not notify you of such modifications and adjustments. Please refer to the real-time information on the official website.

\* All specifications are subject to change without notice.

© 2023 Shanghai Huace Navigation Technology Ltd. All rights reserved. The CHCNAV and CHCNAV logo are trademarks of Shanghai Huace Navigation Technology Limited. All other trademarks are the property of their respective owners. Revision September 2023.

WWW.CHCNAV.COM | MARKETING@CHCNAV.COM

CHC Navigation Headquarter  
Shanghai Huace Navigation Technology Ltd.  
577 Songying Road, Qingpu,  
201703 Shanghai, China  
+86 21 54260273

CHC Navigation Europe  
Infopark Building, Sétány 1,  
1117 Budapest, Hungary  
+36 20 421 6430  
Europe\_office@chcnv.com

CHC Navigation USA LLC  
6380 S. Valley View Blvd, Suite 246,  
Las Vegas, NV 89118, USA  
+1 702 405 6578

CHC Navigation India  
409 Trade Center, Khokhra Circle,  
Maninagar East, Ahmedabad,  
Gujarat, India  
+91 90 99 98 08 02